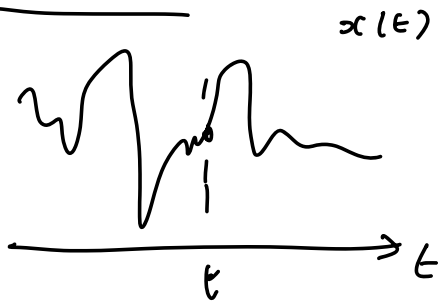


Cours du 5/10



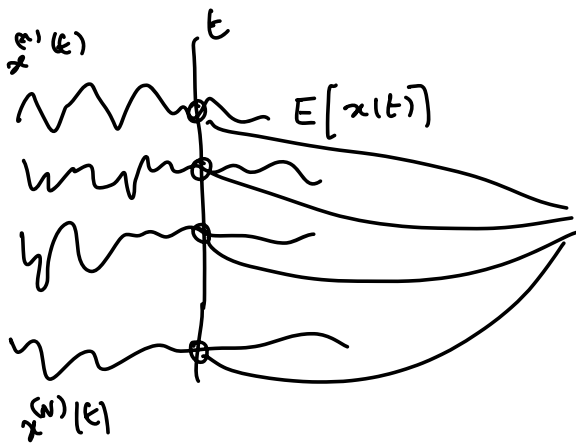
x variable aléatoire

$$E[g(x)]$$

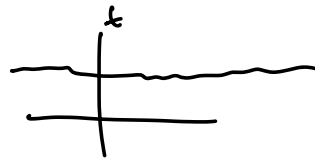
$$\sum_i g(x_i) P[X=x_i]$$

$$\int g(x) p(x) dx$$

densité de probabilité de X

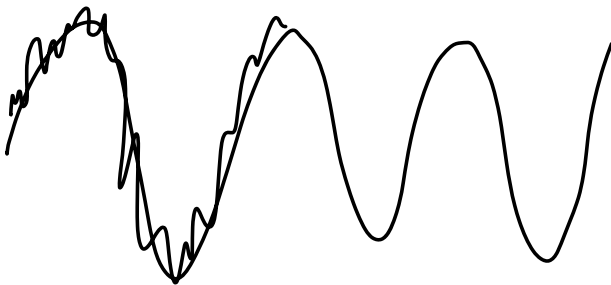


$$\frac{1}{N} \sum_{i=1}^N x^{(i)}(t) \xrightarrow{N \rightarrow +\infty} E[x(t)]$$



Variance d'un signal

$$E[x^2(t)] - E[x(t)]^2$$



Exemple 1

$$x(t) = A \cos(2\pi f_0 t + \theta)$$

$$f_0 = 50 \text{ Hz}$$

$$A = 220\sqrt{2}$$

θ variable aléatoire uniforme
sur $]0, 2\pi[$



$$p(\theta) = \begin{cases} \frac{1}{2\pi} & \theta \in]0, 2\pi[\\ 0 & \text{ailleurs} \end{cases}$$

ou 2π
 $x(t)$ stationnaire ?

Proyenne $E[x(t)] = E[A \cos(2\pi f_0 t + \theta)] = A E[\underbrace{\cos(2\pi f_0 t + \theta)}_{g(\theta)}]$

$$= A \int g(\theta) p(\theta) d\theta$$

$$= A \int_0^{2\pi} \cos(2\pi f_0 t + \theta) \frac{1}{2\pi} d\theta$$

$$= \frac{A}{2\pi} \left[\sin(2\pi f_0 t + \theta) \right]_0^{2\pi}$$

$$= \textcircled{0} = 0$$

$E[x(t)] = 0$
indépendant de t

$x^*(t-\tau) = x(t-\tau)$

$$E[x(t) x^*(t-\tau)] = E[A \cos(2\pi f_0 t + \theta) \overbrace{A \cos[2\pi f_0 (t-\tau) + \theta]}^{x^*(t-\tau) = x(t-\tau)}]$$

$$\cos a \cos b = \frac{1}{2} \cos(a+b) + \frac{1}{2} \cos(a-b)$$

$$= A^2 E\left[\frac{1}{2} \cos(2\theta + 4\pi f_0 t - 2\pi f_0 \tau) \right.$$

$$\left. + \frac{1}{2} \cos(2\pi f_0 \tau) \right]$$

$$= \frac{A^2}{2} \left[\int_0^{2\pi} \cos(2\theta + 4\pi f_0 t - 2\pi f_0 \tau) d\theta + \int_0^{2\pi} \frac{\cos(2\pi f_0 \tau)}{2\pi} d\theta \right]$$

$$= \frac{A^2}{2} (0 + \cos(2\pi f_0 \tau))$$

$E[x(t) x^*(t-\tau)] = \frac{A^2}{2} \cos(2\pi f_0 \tau)$

ind de t

$$E[x(t)] \text{ ind de } t$$

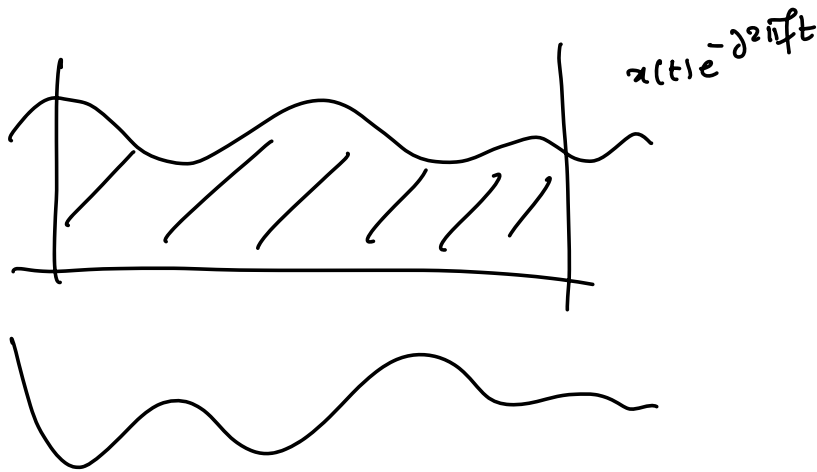
$$E[x(t)x^*(t-\tau)] \text{ ind de } t$$

\Rightarrow

$x(t)$ stationnaire

Transformée de Fourier

$$\int_{\mathbb{R}} x(t) e^{-j2\pi ft} dt$$



Définition : densité spectrale de puissance d'un signal aléatoire

$$S_x(f) = \text{TF} [R_x(\tau)]$$

~~TF [x(t)]~~

$$= \int_{\mathbb{R}} R_x(\tau) e^{-j2\pi f \tau} d\tau$$

définit le spectre des signaux aléatoires

$$R_x(\tau) = \frac{A^2}{2} \cos(2\pi f_0 \tau) \xrightarrow{\text{Take}} S_x(f) = \text{TF} [R_x(\tau)]$$

$$= \frac{A^2}{4} [\delta(f-f_0) + \delta(f+f_0)]$$

$$\Delta_x(f) = \mathcal{TF}[R_x(\tau)] \Rightarrow R_x(\tau) = \mathcal{IF}^{-1}(\Delta_x(f))$$

$$= \int R_x(\tau) e^{-j2\pi f\tau} d\tau \quad = \int \Delta_x(f) e^{+j2\pi f\tau} df$$

$$R_x(0) = \int \Delta_x(f) df$$

$$d^2[x(t_1), x(t_2)] = \|x(t_1) - x(t_2)\|^2$$

$$= \langle x(t_1) - x(t_2), x(t_1) - x(t_2) \rangle$$

$$= \langle x(t_1), x(t_1) \rangle + \langle x(t_2), x(t_2) \rangle - \langle x(t_1), x(t_2) \rangle - \langle x(t_2), x(t_1) \rangle$$

$$E[x(t_1)x^*(t_1)] = E[|x(t_1)|^2]$$

$$- \langle x(t_1), x(t_2) \rangle - \langle x(t_2), x(t_1) \rangle$$

$$E[x(t_1)x^*(t_2)] = R_x(\tau)$$

Remarque
 $E[x(t_1)x^*(t_2)] = R_x(t_1 - t_2)$
 $\tau = t_1 - (t_2)$

$$E[x(t_2)x^*(t_2)] = R_x(0)$$

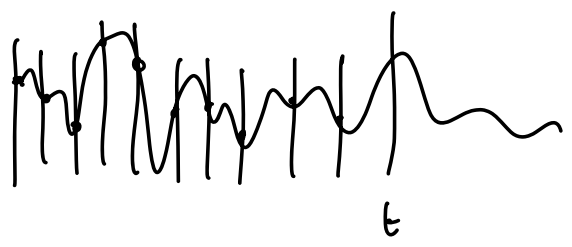
$$d^2[x(t_1), x(t_2)] = R_x(0) + R_x(0) - R_x(\tau) - \underbrace{R_x(-\tau)}_{R_x^*(\tau)}$$

Si $x(t)$ réel

$$d^2[x(t_1), x(t_2)] = 2 [R_x(0) - R_x(\tau)]$$

Ergodicité

$$E[x(t)] = ?$$

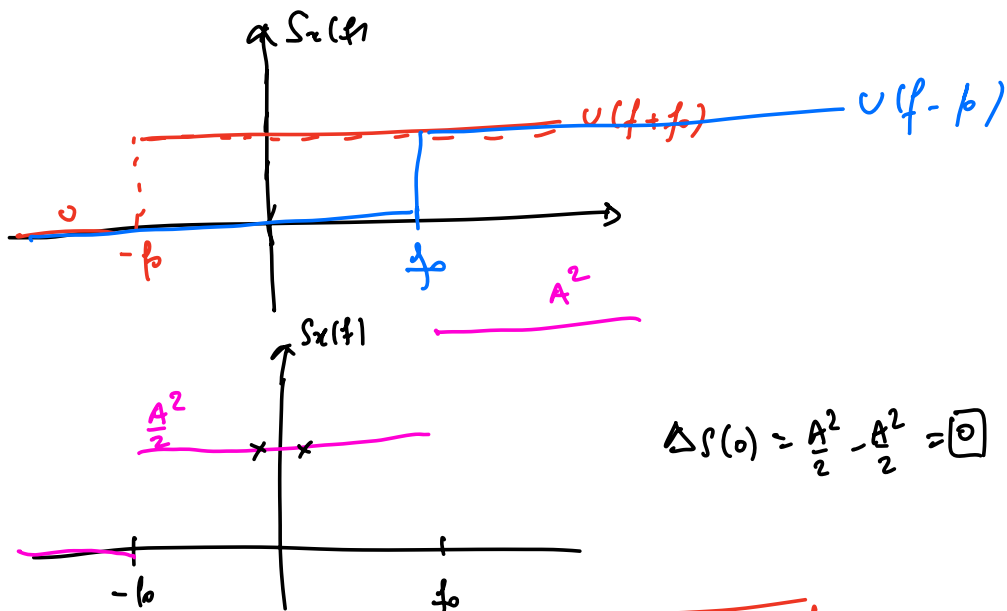


$$(v(f))' = \delta(f)$$

$$\int_0^1 1$$

$$\Delta_x(f) = \frac{A^2}{2} [f(f-b_0) + f(f+b_0)]$$

$$\Delta_x(f) = \frac{A^2}{2} [v(f-b_0) + v(f+b_0)]$$



$$\Delta S(0) = \frac{A^2}{2} - \frac{A^2}{2} = 0$$

Exemple de signal non ergodique

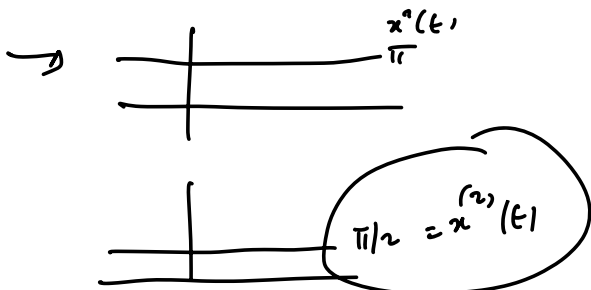
$x(t) = \theta$ θ variable aléatoire uniforme sur $]0, 2\pi[$.

$$E(x(t)) = E(\theta) = \frac{\pi}{2}$$

$$E(x(t)x(t-c)) = E(\theta^2) = \frac{(2\pi)^2}{12} = \frac{\pi^2}{3}$$

$$\int_0^{2\pi} \frac{\theta}{2\pi} d\theta = \frac{1}{2\pi} \left[\frac{\theta^2}{2} \right]_0^{2\pi} = \frac{\pi}{2}$$

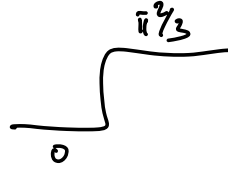
$$\int_0^{2\pi} \frac{\theta^2}{2\pi} d\theta = \frac{1}{2\pi} \left[\frac{\theta^3}{3} \right]_0^{2\pi} = \frac{\pi^2}{3}$$



$$R_x(t) = \frac{\pi^2}{3}$$

$$\Delta x(t) = \frac{\pi^2}{3} \delta(t)$$

$$S_x(t) = \frac{\pi^2}{3} U(t)$$



$$\Delta S_x(0) = \frac{\pi^2}{3} \neq E[x^2(t)] = \pi^2$$